TIGER PAN & TILT SYSTEM

TIGER

The TIGER is a stable and sophisticated pedestal adapted to immobile vantage points and extreme weather conditions.

TTIGER is a single heavy-duty unit, capable of supporting payloads up to 150kg without losing precision and designed to be a true REAL-TIME long range observation system.







TIGER PAN & TILT SYSTEM

The Tiger is a stable and sophisticated pedestal adapted to immobile vantage points and extreme weather conditions. TIGER is a single heavy-duty unit, capable of supporting payloads up to 150Kg without losing precision and designed to be a true REAL-TIME long range observation system. Built-in control electronics and software provides a precise, smooth motion at all speeds, while an integrated slipring allows a continuous rotation of the pan axis.





TIGER PAN & TILT SYSTEM, General Specification

Product Line:				
TIGER				
Туре	U- Shape			
Payload Type	Camera			
Azimuth / Pan movement	Nx360° or up to 345° (no slip-ring)			
Elevation / Tilt movement	Up to 360°			
Self-Weight [kg]	~110			
Control mode	Speed / Position			
Communication	Ethernet TCP / RS232 / RS422 / Rs485			
Environmental protection	IP65, Humidity, Temperatures & more			
Power consumption [V] [A]	48V & 8Amp			
max Payload (balanced) [kg]	150			
Max Acceleration [°/Sec²]	150			
Speed (balanced) [°/Sec]	0.01-360			
Position Accuracy [°]	±0.001			
Position Sensor Encoder	Absolute / Incremental			
Resolution [°]	0.000005/0.0013			
Stabilizat	ion systems			
Stabilization Accuracy [°]	Payload dependent			
Stabilization Sensor	IMU / FOG			
Tracker systems				
GPS Stabilization by Datum point	Payload dependent			
GPS Units	LLA / UTM			
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^(*) Payload dependent

^(**) mechanics & power dependent

^(***) mass, balance & power dependent

[•] Control Interface, GPS and Stabilization – Optional



TIGER PAN & TILT SYSTEM, Environmental Specification

Storage Temperature [°C]	-40 ~ +70			
Operational Temperature [°C]	-40 ~ +55			
Humidity [°C @ %RH]	+32 to +55 @ 95±4			
Sal	t Fog Exposure			
Salt Solution Concentration [%]	5±1			
Salt Fog PH	6.5 to 7.2			
Salt Fog Fallout Rate [ml/8ocm2/hr]	1-3			
Duration [hr]		48		
Temperature [°C]		+35±2	2	
Salt F	og Drying Period			
Temperature [°C]		+25±10		
Duration [hr]		48		
Humidity [%RH]		<50		
So	olar Radiation			
Temperature [°C]	+32 to +49			
Max Intensity [W/m2]	1120			
Cycles		3		
В	Blowing Dust			
Wind Velocity [m/sec]	8.9			
Dust Concentration [g/m2]	10.6±7			
Relative Humidity [%]	<30			
Temperature [°C] [*test 1 & test 2]	25 70			
E	Blowing Rain			
Wind Velocity [m/sec]	18			
Rain Rate [mm/min]	>1.7			
Droplet Size Dia. [mm]	0.5 to 4.5			
Duration [min/face]		30		
No. of Faces	4			
Vibration				
Axes	3 (X,Y,Z)			
Vibration Level [grms]	X=2.4 Y=:	1.3	Z=3.6	
Frequency Range [Hz]	5-500			
Vibration Time per Axis [min]	60			
	I			



lcing					
Ice Thickness [mm] Ice Thickness [mm]					
Temperature [°C]	Temperature [°C]				
Blowing Sand					
Wind Velocity [m/sec]	18				
Sand Concentration [g/m³]	1.1±0.3				
Humidity [%RH]	<30				
Temperature [°C]	+55±2				
No. of Faces	1				
Duration [min/face]	90				
Mechanica	l Shock				
Axes	3 (±X, ±Y, ±Z)				
Shock Form	Saw-Tooth				
Shocks per Axis	6 (3 each direction)				
Pulse Duration [mSec]	11				
Total Shocks	18				
Shock Amplitude [g]	40				

TIGER PAN & TILT SYSTEM, Stabilized Version

Product Line: TIGER - Stabilized		
Stabilization Accuracy [°]	±0.1 - ±1 (*payload & mechanics dependent)	
	IMU:	
	- Gyro range: ±2,000°/Sec	
	- Accelerometer range: ±16g	
Stabilization Sensor	- Magnetometer range: ±2.5Gauss	
	<u>FOG</u> :	
	- Gyro range: ±490°/Sec	
	- Accelerometer range: ±10g	



TIGER PAN & TILT SYSTEM, Tracker Version

Product Line: TIGER - Tracker			
GPS Stabilization Accuracy [°]	±0.1 - ±1 (*mechanics and antenna spread dependent)		
GPS Sensor	- Updates Rate: 5Hz		
	- Receiver Type: GNSS		
	- Static Accuracy (Heading): 0.3° RMS		
	- Static Accuracy (Pitch / Roll): 0.5° RMS		
	- Dynamic Accuracy (Heading): 0.3° RMS		
	- Dynamic Accuracy (Pitch / Roll): 0.1° RMS		

TIGER PAN & TILT SYSTEM, GUI Pannell

Parameter	Specification	Notes
Communication	Ethernet (TCP)	
Operation mode	Manual / Stabilized / Tracker	
Control mode	Speed / Position	
Operation	Manual arrows controlled by user	
Presets	Up to 15 saved points	
Targets	Up to 15 saved GPS targets	Tracker only
Register Status	Online state of system registers	
Software limit	User defined software limit switches for both axes	
switches		
Homing	Homing position declaration	
Scanning modes	Zigzag, Square and Snake	
IP Setting	Ability changing system IP addresses & port	



TIGER PAN & TILT SYSTEM, MICD

